# Development of a retrievable sonobuoy system for whale sounds recording in polar region

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## **ABSTRACT**

A newly retrievable sonobuoy system to record underwater whale sounds in the Antarctic was successfully developed in the JARPA program. Recording of about 7 hours at 6 stations, about 10 hours at 6 stations and about 19 hours at 15 stations were carried out in 1997/98, 1998/99 and 1999/2000 JARPA surveys, respectively. The spar-typed sonobuoy was employed in the 1998/99 JARPA to minimize low frequency "mechanical self-noise" caused by up and down movement of the hydrophone with 10 m cable. Preliminary data analysis shows that the system obtained clear sounds of blue (minimum total 150 calls), fin (400 calls) and humpback (3 calls) whales within short total recording time without substantial technical problems. A lightweight positioning system will be added to the system in the near future so that accurate position can be recorded. These acoustic data will contribute to the whale sound studies in the Southern Ocean such as the IWC/SOWER blue whale research program.

## INTRODUCTION

Acoustic experiments to record whale sounds using a retrievable sonobuoy system were conducted in the Japanese Whale Research Program under Special Permit in the Antarctic (JARPA) from the 1997/98 to 1999/2000 seasons (Ishikawa et al., 1998, 2000, Nishiwaki et al., 1999). The Institute of Cetacean Research (ICR) developed a specifically designed system to record whale sounds in the Antarctic in cooperation with the System Giken Company Ltd., Kanagawa, Japan. Considering field handing, environmental issues and budgetary constraints, a retrievable sonobouy system was selected. This paper describes the newly developed "ICR sonobuoy system" and presents the results of experiments in JARPA surveys.

#### DEVELOPMENT OF SONOBUOY SYSTEM

A summary of the ICR sonobuoy system specifications during each cruise is shown in Table 1. Fig. 1 shows the shape of the system used in each cruise. Details of the development of the system are summarized below.

## The float type system with GPS used in the 1997/98 cruise

The float type system (sonobuoy length was 700mm, diameter was 140mm) was used in this season. The system consisted of a DAT recorder (SONY-TCD-D100), an alkali battery, a hydrophone (5Hz to 25kHz,  $\pm$ 3db) with cable (10m) and a GPS transmitter to detect position of sonobouy. Consumption of alkali battery power was unexpectedly high due to low water temperature. Recording conditions were inferior especially for low frequencies because of low frequency "mechanical self-noise" that occurred when a hydrophone with a 10m cable that was suspended from the sonobuoy was moved up and down by the waves.

# Application of the spar type system used in the 1998/99 cruise

The spar buoy type system (length was 4,500mm, diameter was 140mm) was adapted to minimize low frequency "mechanical self-noise". The system consisted of a DAT recorder, a lithium battery, a hydrophone (5Hz to 25kHz,  $\pm$ 3db) with cable (10m) and a GPS buoy. The lithium battery was used

because it had a longer life than the alkali battery in the low water temperature environment. Preliminary analyses of 1998/99 data showed that the "mechanical self-noise" was much reduced compared to the 1997/98 data. Noise reduction was considered as adoption of the spar buoy.

# Lightweight modifications in the 1999/2000 cruise

The spar buoy type system (length was 3,000mm, diameter was 140mm) was used as in the 1998/1999 season but the length was 1500mm shorter than that in 1998/1999 for easier handling in the field. The system consisted of a DAT recorder, a lithium battery, a low frequency hydrophone with a cable (10m) and a radar reflector. The radar reflector was used instead of the GPS transmitter because GPS transmitter was relatively heavy (Fig. 3). Field handling efficiency of the sonobuoy system was significantly enhanced (Fig. 4). Although deployment and recovering operations were improved by these modifications, movement range of the research vessel was reduced (maximum 6 miles that was equivalent to radar range). Since an accurate position of the sonobuoy system during recording is desired, a lightweight positioning system will be added to the system in the near future.

## RESULTS OF WHALE SOUNDS RECORDING

The sonobuoy experiments were mainly conducted during blue whale experiments of photo ID and biopsy, when blue whales were sighted. Table 2 shows the summary of the ICR sonobuoy experiments in JARPA from the 1997/98 to the 1999/2000 cruises. Recording of about 7 hours at 6 stations, about 10 hours at 6 stations and about 19 hours at 15 stations were carried out in 1997/98, 1998/99 and 1999/2000 JARPA surveys, respectively.

Clear calls were recorded 150 times for blue, 400 times for fin and 3 times for humpback whales within about 10 hours recording in the 1998/99 cruise. The spectrograms of blue and fin whales are shown in Fig. 5. Further analyses of 1998/99 data and preliminary analyses in 1999/2000 data are planned in the near future. These acoustic data in the Antarctic will contribute to studies on geographical variations of whale sounds such as those being conducted as part of the IWC/SOWER blue whale research program. Our blue whales vocalization data will be useful to separate true blue whales from pygmy blue whales

### ACKNOWLEDGEMENTS

We sincerely thank Dr. T. Akamatsu of the National Research Institute of Fisheries Engineering and Mr. P. Ensor, the SOWER cruise leader, for their various suggestions related to the development of sonobuoy system. Our sincere thanks are also due to the staffs of the System Giken Company, Ltd. who were involved in the development of the sonobuoy system. We are indebted to the captains, crews and researchers who conducted the JARPA surveys.

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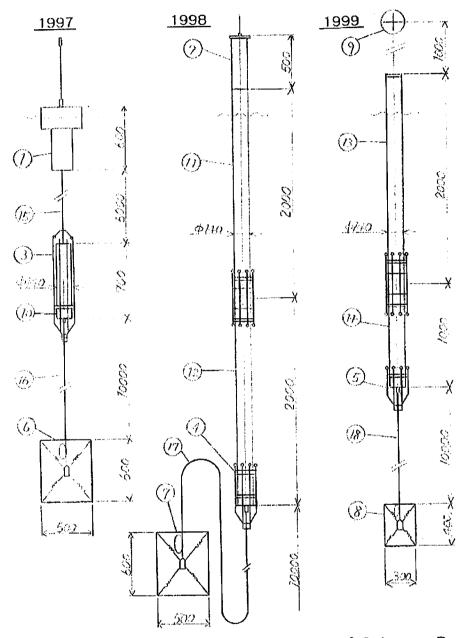
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Table. 1. Developments of the ICR sonobuoy system.

Item	1997/98	1998/99	1999/2000
Sonobuoy type	Float type	Spar buoy type	Spar buoy type
Sonobuoy length (mm)	700	4500	3000
Sonobuoy diameter (mm)	140	140	140
Recorder (SONY)	DAT(TCD-D100)	DAT(TCD-D100)	DAT(TCD-D100)
Battery type	Alkali	Lithium	Lithium
Hydrophone	5Hz - 25kHz	5Hz - 25kHz	5Hz - 25kHz
Hydrophone gauge (mm)	500*500*600	500*500*600	300*300*400
Positioning system	GPS	GPS	Rader reflector

Table. 2. Summary of the ICR sonobuoy experiment in JARPA 1997/98 to 1999/2000 cruises.

Biological sound 1)	1	1	1	1	ı	1	1	Humpback	Blue	Fin	Blue	Fin	1	1	*	*	*	*	÷	<b>€</b> +	*	*	*	*		*			*		*	*	*	*	
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Recording minutes	20	122	38	62	85	101	86	68	136		69		64	136	82	99	116	84	ou	9 6	26	84	104	64		80			74		72	64	26	40	
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Target species	Test	Humpback	Test	Fin	Blue	Test	Test	Humpback	Blue		Blue	Humpback	S.Bottlenose	Fin	Test	Blue	Blue	Blue	Sperm	anio d	Blue	Humpback	Humpback	Blue	Blue	Blue	Blue	Blue	Minke	Minke	Right	Baleen whales	Right	Humpback	Killer
Sighting no.		10		17	17		1	10	4		13		2	18	ſ	2	6	12	u	<b>)</b>	۰ م	4	19	16	17	10	1 2	21	4 4	2	2	18	20	6	
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Recovery position Lat.		82.341	84.40	86.31	93.17	63.553	127.357	148.136	148.571		149.203		161.433	177.04	41.084	46.547	60.141	61.002	50 967	102.60	61.304	82.455	103.015	104.155		120.426			116.399		114 - 30.6	111.269	103.001	97.369	
very		S	S	S	S	S	S	v.	S		S		S	S	S	S	S	S	U	<b>2</b> C	0	S	S	S		S			S		S	S	S	S	
Reco Lat.		62.447	61.22	60.17	63.06	65.174	60.134	65.091	65.364		65.371		65.543	68.446	61.250	63.197	62.157	62.238	69 019	210.20	50.77	61.077	62.128	62.528		63.566			64.583		64.354	65.134	64.17	64.095	
Recovery time	830	1551	741	1659	1300	1714	1335	1506	948		1227		927	1513	815	1704	1343	1717	050	1445	1445	1800	1520	1019		1526			903		1038	1244	1709	1835	
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Deploy position at.		82.353	84.403	86.314	93.172	63.538	127.353	148.131	148.568		149.203		161.429	177.013	41.085	46.537	60.136	965.09	50 261	03.501	01.293	82.452	103.036	104.128		102.420			116.402		114.307	111.268	103.000	97.378	
l fold		S	S	S	S	S	S	v.	S		S		S	S	S	S	S	S	U	י כ	0	S	S	S		S			S		S	S	S	S	
De Lat.		62.445	61.223	60.167	63.064	65.172	60.131	65.089	65.363		65.373		65.542	68.44	61.251	63.195	62.156	62.236	62 014	50.00	907.00	61.079	62.119	62.528		63.567			64.583		64.354	65.132	64.171	64.094	
Deploy time	810	1403	722	1607	1115	1550	1213	1356	742		1131		823	1307	700	1606	1228	1605	100	1000	1320	1645	1342	923		1413			756		933	1149	1623	1758	
Date	19980104	19980105	19980107	19980109	19980112	19980308	19990113	19990120	19990121		19990121		19990219	19990305	19991211	19991213	19991219	19991219	10001991	19991221	19991224	20000104	20000113	20000114		20000122			20000208		20000210	20000211	20000216	20000219	
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Area	N	2	2	$\geq$	2	$\geq$	WN-V	WN-V	NN-V		NN-V		NS-N	V-SE	IIIE	IIE	IIE	IIE	H		IIE	IV-NW	IV-NE	IV-NE		IV-NE			IV-SE		IV-SE	IV-SE	IV-SE	IV-SW	



The Institute of Cetacean Research

GPS radio 1,2	chloroethylene pipe	10,11,12,13	TRANSITION of SONOBOUY
recorder 3,4,5 wave reciver 6,7,8	SUS pipe	14 15	drawing No.4
reflector 9	cable	16,17,18	date:26.Apr.2000 draw:Wada

Fig. 1. Outline of the newly developed ICR sonobuoy system from 1997/98 to 1999/2000.

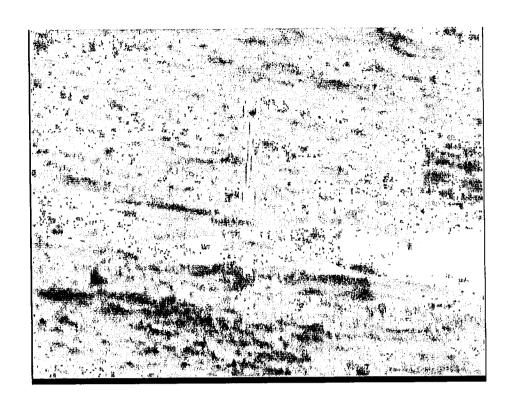


Fig.2. Photograph of the ICR sonobuoy system in 1999/2000 JARPA.

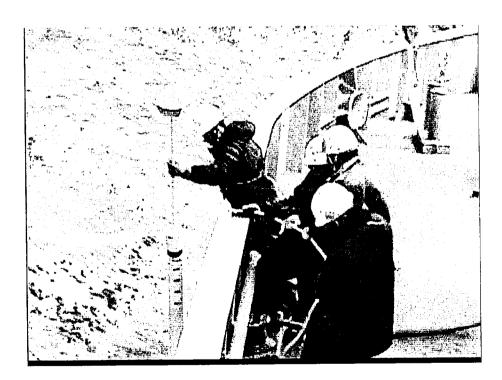
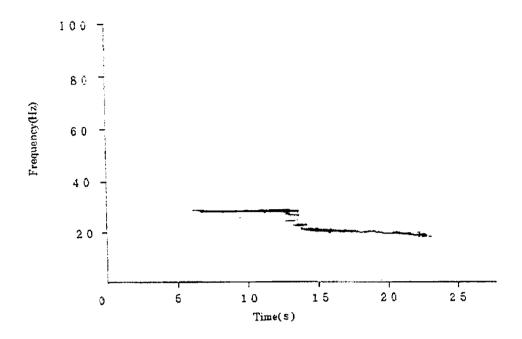


Fig.3. Photograph of deployment the ICR sonobuoy system in 1999/2000 JARPA.



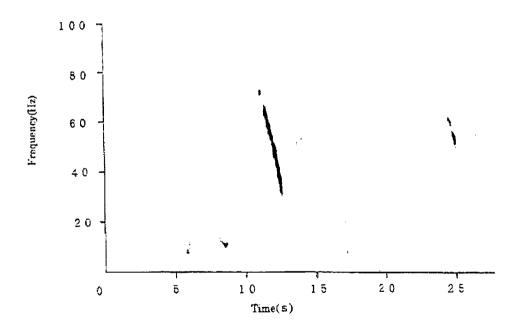


Figure 5. Spectrogram examples of whale sounds recorded during JARPA 1998/99 cruise. Top panel shows the spectrogram of a typical blue whale call as recorded in Area V on 21 January 1999 when blue whales were seen. Bottom panel shows the spectrogram of a typical fin whale call as recorded in Area V on 21 January 1999.